

# EECS 275 Matrix Computation

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Lecture 17

# Overview

- QR algorithm without shifts
- Simultaneous iteration
- QR algorithm with shifts
- Wilkinson shifts

# Reading

- Chapter 28-29 of *Numerical Linear Algebra* by Lloyd Trefethen and David Bau
- Chapter 8 of *Matrix Computations* by Gene Golub and Charles Van Loan

# The QR algorithm

- The QR algorithm, dating to the early 1960s, is one of the jewels of numerical analysis
- In its simplest form, it can be viewed as a stable procedure for computing QR factorizations of the matrix powers  $A$ ,  $A^2$ ,  $A^3$ ,  $\dots$
- Useful for solving eigenvalue problems

## Pure QR algorithm

- “Pure” QR algorithm:

$$A^{(0)} = A$$

**for**  $k = 1, 2, \dots$  **do**

$$Q^{(k)}R^{(k)} = A^{(k-1)} \quad // \text{ QR factorization of } A^{(k-1)}$$

$$A^{(k)} = R^{(k)}Q^{(k)} \quad // \text{ Recombine factors in reverse order}$$

**end for**

- Take a QR factorization, multiply the computed factors  $Q$  and  $R$  together in the reverse order  $RQ$ , and repeat
- Under suitable assumptions, this simple algorithm converges to a Schur form for the matrix, upper triangular if  $A$  is arbitrary, diagonal if  $A$  is Hermitian
- Here we assume  $A$  is real and symmetric with real eigenvalues  $\lambda_j$  and orthonormal eigenvectors  $\mathbf{q}_j$ , i.e., interest in the convergence of the matrices  $A^{(k)}$  to diagonal form

## QR algorithm (cont'd)

- The QR algorithm

$$Q^{(k)}R^{(k)} = A^{(k-1)} \quad // \text{ QR factorization of } A^{(k-1)}$$
$$A^{(k)} = R^{(k)}Q^{(k)} \quad // \text{ Recombine factors in reverse order}$$

- Carry out similarity transformation ( $A \mapsto X^{-1}AX$ )
  - ▶ triangularize  $A^{(k)}$  by forming  $R^{(k)} = (Q^{(k)})^\top A^{(k-1)}$
  - ▶ multiply on the right by  $Q^{(k)}$  gives  $A^{(k)} = (Q^{(k)})^\top A^{(k-1)}Q^{(k)}$
- Recall if  $X \in \mathbb{C}^{m \times m}$  is nonsingular, then the map  $A \mapsto X^{-1}AX$  is a similarity transformation of  $A$
- Also recall an eigendecomposition of a square matrix  $A$  is a factorization  $A = X\Lambda X^{-1}$  where  $X$  is a nonsingular and  $\Lambda$  is diagonal

## QR algorithm (cont'd)

- Like Rayleigh quotient iteration, the QR algorithm for real symmetric matrices converges cubically
- However, it must be modified by introducing shifts at each step
- The use of shifts is one of the three modifications required to bring it closer to practical algorithm
  - ▶ before starting the iteration,  $A$  is reduced to tridiagonal form (e.g., using Hessenberg reduction)
  - ▶ instead of  $A^{(k)}$ , a shifted matrix  $A^{(k)} - \mu^{(k)}I$  is factored at each step, where  $\mu^{(k)}$  is some eigenvalue estimate
  - ▶ whenever possible, and in particular whenever an eigenvalue is found, the problem is deflated by breaking  $A^{(k)}$  into submatrices

# Practical QR algorithm

- Practical QR algorithm

$(Q^{(0)})^T A^{(0)} Q^{(0)} = A$  //  $A^{(0)}$  is a tridiagonalization of  $A$

**for**  $k = 1, 2, \dots$  **do**

Pick a shift  $\mu^{(k)}$  // e.g., choose  $\mu^{(k)} = A_{mm}^{(k-1)}$

$Q^{(k)} R^{(k)} = A^{(k-1)} - \mu^{(k)} I$  // QR factorization of  $A^{(k-1)} - \mu^{(k)} I$

$A^{(k)} = R^{(k)} Q^{(k)} + \mu^{(k)} I$  // Recombine factors in reverse order

If any off-diagonal element  $A_{j,j+1}^{(k)}$  is sufficiently close to zero,  
set  $A_{j,j+1} = A_{j+1,j} = 0$  to obtain

$$\begin{bmatrix} A_1 & 0 \\ 0 & A_2 \end{bmatrix} = A^{(k)}$$

and apply the QR algorithm to  $A_1$  and  $A_2$

**end for**

- The QR algorithm with well-chosen shifts has been the standard method for computing all eigenvalues of a matrix since the early 1960



# Unnormalized simultaneous iteration

- Idea: apply the power iteration to several vectors at once (also known as **block power iteration**)
- Suppose we start with a set of  $n$  linearly independent vectors  $\mathbf{v}_1^{(0)}, \dots, \mathbf{v}_n^{(0)}$
- As  $A^k \mathbf{v}_1^{(0)}$  converges as  $k \rightarrow \infty$  (under suitable assumptions) to the eigenvector corresponding to the largest eigenvalue of  $A$  in absolute value
- The space  $\langle A^k \mathbf{v}_1^{(0)}, \dots, A^k \mathbf{v}_n^{(0)} \rangle$  should converge (under suitable assumptions) to the space  $\langle \mathbf{q}_1, \dots, \mathbf{q}_n \rangle$  spanned by the eigenvectors  $\mathbf{q}_1, \dots, \mathbf{q}_n$  of  $A$  corresponding to the  $n$  largest eigenvalues in absolute value

## Unnormalized simultaneous iteration (cont'd)

- In matrix notation, define  $V^{(0)}$  to be the  $m \times n$  initial matrix

$$V^{(0)} = \begin{bmatrix} \mathbf{v}_1^{(0)} & \cdots & \mathbf{v}_n^{(0)} \end{bmatrix}$$

and define  $V^{(k)}$  to be the result after  $k$  applications of  $A$ :

$$V^{(k)} = A^k V^{(0)} = \begin{bmatrix} \mathbf{v}_1^{(k)} & \cdots & \mathbf{v}_n^{(k)} \end{bmatrix}$$

- Extract a well-behaved basis for this space by computing a reduced QR factorization of  $V^{(k)}$

$$\hat{Q}^{(k)} \hat{R}^{(k)} = V^{(k)}$$

where  $\hat{Q}^{(k)}$  and  $\hat{R}^{(k)}$  have dimensions  $m \times n$  and  $n \times n$ , respectively

- As  $k \rightarrow \infty$ , the columns should converge to eigenvectors  $\pm \mathbf{q}_1$ ,  $\pm \mathbf{q}_2, \dots, \pm \mathbf{q}_n$

## Analysis of simultaneous iteration

- If we expand  $\mathbf{v}_j^{(0)}$  and  $\mathbf{v}_j^{(k)}$  in the eigenvectors of  $A$ , we have

$$\begin{aligned}\mathbf{v}_j^{(0)} &= a_{1j}\mathbf{q}_1 + \cdots + a_{mj}\mathbf{q}_m \\ \mathbf{v}_j^{(k)} &= \lambda_1^k a_{1j}\mathbf{q}_1 + \cdots + \lambda_m^k a_{mj}\mathbf{q}_m\end{aligned}$$

- Simple convergence results will hold if two conditions are satisfied
  - ▶ the leading  $n + 1$  eigenvalues are distinct in absolute value:

$$|\lambda_1| > |\lambda_2| > \cdots > |\lambda_n| > |\lambda_{n+1}| \geq |\lambda_{n+2}| \geq \cdots \geq |\lambda_m|$$

- ▶ the collection of expansion coefficients  $a_{ij}$  is nonsingular. Define  $\hat{Q}$  as the  $m \times n$  matrix whose columns are the eigenvectors  $\mathbf{q}_1, \mathbf{q}_2, \dots, \mathbf{q}_n$ . We assume the following

All the leading principal submatrices of  $\hat{Q}^T V^{(0)}$  are nonsingular

- ▶ namely, the upper-left  $1 \times 1, 2 \times 2, \dots, n \times n$  submatrices are nonsingular

## Simultaneous iteration

- As  $k \rightarrow \infty$ , the vectors  $\mathbf{v}_1^{(k)}, \dots, \mathbf{v}_n^{(k)}$  all converge to multiples of the same dominant eigenvector  $\mathbf{q}_1$  of  $A$
- Thus, although the space they span  $\langle \mathbf{v}_1^{(k)}, \dots, \mathbf{v}_j^{(k)} \rangle$  converges to something useful, these vectors constitute a highly ill-conditioned basis of that space
- Need to orthonormalize at each step rather than once for all
- Use a different sequence of matrices  $Z^{(k)}$  rather than  $V^{(k)}$  as before

$\hat{Q}^{(0)} \in \mathbb{R}^{m \times n}$  with orthonormal columns

**for**  $k = 1, 2, \dots$  **do**

$$Z = A\hat{Q}^{(k-1)}$$

$$\hat{Q}^{(k)}\hat{R}^{(k)} = Z \quad // \text{ reduced QR factorization of } Z$$

**end for**

- The column spaces of  $\hat{Q}^{(k)}$  and  $Z^{(k)}$  are the same, both being equal to the column space of  $A^k \hat{Q}^{(0)}$

## Simultaneous iteration $\iff$ QR Algorithm

- The QR algorithm is equivalent to simultaneous iteration applied to a full set of  $n = m$  initial vectors, namely, the identity,  $\hat{Q}^{(0)} = I$
- Since the matrices  $\hat{Q}^{(k)}$  are now square, we are dealing with full QR factorization and can drop the hats on  $\hat{Q}^{(k)}$  and  $\hat{R}^{(k)}$
- Will replace  $\hat{R}^{(k)}$  by  $R^{(k)}$  but  $\hat{Q}^{(k)}$  by  $\underline{Q}^{(k)}$  to distinguish the Q matrices of simultaneous iteration from those of the QR algorithm

# Simultaneous iteration and unshifted QR algorithm

Simultaneous iteration

$$\underline{Q}^{(0)} = I \quad (1)$$

$$\underline{Z} = \underline{A}\underline{Q}^{(k-1)} \quad (2)$$

$$\underline{Z} = \underline{Q}^{(k)}\underline{R}^{(k)} \quad (3)$$

$$\underline{A}^{(k)} = (\underline{Q}^{(k)})^\top \underline{A}\underline{Q}^{(k)} \quad (4)$$

Unshifted QR algorithm

$$\underline{A}^{(0)} = A \quad (5)$$

$$\underline{A}^{(k-1)} = \underline{Q}^{(k)}\underline{R}^{(k)} \quad (6)$$

$$\underline{A}^{(k)} = \underline{R}^{(k)}\underline{Q}^{(k)} \quad (7)$$

$$\underline{Q}^{(k)} = \underline{Q}^{(1)}\underline{Q}^{(2)} \dots \underline{Q}^{(k)} \quad (8)$$

For both algorithms, we define one  $m \times m$  matrix  $\underline{R}^{(k)}$

$$\underline{R}^{(k)} = \underline{R}^{(k)}\underline{R}^{(k-1)} \dots \underline{R}^{(1)} \quad (9)$$

## Theorem

*The above processes generate identical sequences of matrices  $\underline{R}^{(k)}$ ,  $\underline{Q}^{(k)}$ , and  $\underline{A}^{(k)}$ , namely, those defined by the QR factorization of the  $k$ -th power of  $A$*

$$\underline{A}^k = \underline{Q}^{(k)}\underline{R}^{(k)} \quad (10)$$

*together with the projection*

$$\underline{A}^{(k)} = (\underline{Q}^{(k)})^\top \underline{A}\underline{Q}^{(k)} \quad (11)$$

# Simultaneous iteration and QR algorithm

## Proof.

The case for  $k = 0$  is trivial. For both simultaneous iteration and the QR algorithm imply  $A^0 = \underline{Q}^{(0)} = \underline{R}^{(0)} = I$  and  $A^{(0)} = A$  from which the results are immediate.

For  $k \geq 1$  for simultaneous iteration

$$A^k = A \underbrace{A^{k-1}}_{(10)} = \underbrace{A \underline{Q}^{(k-1)}}_{(2)(3)} \underline{R}^{(k-1)} = \underline{Q}^{(k)} \underline{R}^{(k)} \underline{R}^{(k-1)} = \underline{Q}^{(k)} \underline{R}^{(k)}$$

For  $k \geq 1$  for the QR algorithm

$$A^k = A \underbrace{A^{k-1}}_{(10)} = \underbrace{A \underline{Q}^{(k-1)}}_{(11)} \underline{R}^{(k-1)} = \underline{Q}^{(k-1)} \underbrace{A^{(k-1)}}_{(6)(8)} \underline{R}^{(k-1)} = \underline{Q}^{(k)} \underline{R}^{(k)}$$

Finally,

$$\underbrace{A^{(k)}}_{(7)} = \underbrace{R^{(k)}}_{(6)} Q^{(k)} = (Q^{(k)})^\top \underbrace{A^{(k-1)}}_{(11)} Q^{(k)} = (\underline{Q}^{(k)})^\top A \underline{Q}^{(k)}$$

## Convergence of the QR algorithm

- Qualitative understanding of (10) and (11) is the key
- First, (10) explains why the QR algorithm can be expected to find eigenvectors: it constructs orthonormal bases for successive powers  $A^k$
- Second, (11) explains why the algorithm finds eigenvalues
- It follows from (11) that the diagonal elements of  $A^{(k)}$  are Rayleigh quotients of  $A$  corresponding to the columns of  $\underline{Q}^{(k)}$
- As these columns converge to eigenvectors, the Rayleigh quotients converge to the corresponding eigenvalues
- Meanwhile, (11) implies that the off-diagonal elements of  $A^{(k)}$  correspond to generalized Rayleigh quotients involving approximations of distinct eigenvectors of  $A$  on the left and the right
- Since these approximations must become orthogonal as they converge to distinct eigenvectors, the off-diagonal elements of  $A^{(k)}$  must converge to zero



## QR algorithm with shifts

- What makes QR iteration works in practice is the introduction of  $A \rightarrow A - \mu I$  at each step
- An implicit connection to the Rayleigh quotient iteration
- The “pure” QR algorithm is equivalent to simultaneous iteration applied to the identity matrix
- In particular, the first column of the result evolves according to the power iteration applied to  $\mathbf{e}_1$
- The “pure” QR algorithm is also equivalent to **simultaneous inverse iteration** applied to a “flipped” identity matrix  $P$ , and the  $m$ -th column of the result evolves according to inverse iteration applied to  $\mathbf{e}_m$
- Let  $Q^{(k)}$  be the orthogonal factor at the  $k$ -th step of the QR algorithm, the accumulated product of these matrices

$$\underline{Q}^{(k)} = \prod_{j=1}^k Q^{(j)} = \begin{bmatrix} \mathbf{q}_1^{(k)} & \mathbf{q}_2^{(k)} & \cdots & \mathbf{q}_m^{(k)} \end{bmatrix}$$

is the same orthogonal matrix that appears at step  $k$  of simultaneous iteration

## QR algorithm with shifts (cont'd)

- Another way to put this is to say  $\underline{Q}^{(k)}$  is the orthogonal factor in a QR factorization

$$A^k = \underline{Q}^{(k)} \underline{R}^{(k)}$$

- If we invert this formula, we calculate

$$A^{-k} = (\underline{R}^{(k)})^{-1} \underline{Q}^{(k)\top} = \underline{Q}^{(k)} (\underline{R}^{(k)})^{-\top}$$

for the second equality we have used the fact that  $A^{-1}$  is symmetric. Let  $P$  denote the  $m \times m$  permutation matrix that reverse row or column order

$$P = \begin{bmatrix} & & & 1 \\ & & 1 & \\ & \dots & & \\ 1 & & & \end{bmatrix}$$

- $PA$  swap rows of  $A$ , and  $AP$  swaps columns of  $A$

## QR algorithm with shifts (cont'd)

- Since  $P^2 = I$ , we have

$$A^{-k}P = (\underline{Q}^{(k)}P)(P(\underline{R}^{(k)})^{-\top}P)$$

where the first factor is this product,  $\underline{Q}^{(k)}P$ , is orthogonal, and the second factor,  $P(\underline{R}^{(k)})^{-\top}P$ , is upper triangular (start with lower triangular matrix  $(\underline{R}^{(k)})^{-\top}$ , flip it top-to-bottom, then flip again left-to-right)

- Can be interpreted as a QR factorization of  $A^{-k}P$
- In other words, we effectively carry out simultaneous iteration on  $A^{-1}$  applied to the initial matrix  $P$ , which is to say, simultaneous inverse iteration on  $A$
- In particular, the first column of  $\underline{Q}^{(k)}P$ , i.e., the last column of  $\underline{Q}^{(k)}$ , is the result of applying  $k$  steps of inverse iteration to the vector  $\mathbf{e}_m$

## Connection with shifted inverse iteration

- The QR algorithm is both simultaneous iteration and simultaneous inverse iteration: the symmetry is perfect
- However, there is a huge difference between power iteration and inverse iteration as the latter can be accelerated arbitrarily through the use of shifts
- The better we can estimate an eigenvalue  $\mu \approx \lambda_J$ , the more we can accomplish by a step of inverse iteration with shifted matrix  $A - \mu I$
- This corresponds to shifts in the simultaneous iteration and inverse iteration
- Let  $\mu^{(k)}$  denote the eigenvalue estimate chosen at the  $k$ -th step of the QR algorithm, the relationship between steps  $k - 1$  and  $k$  of the shifted QR algorithm is

$$\begin{aligned} A^{(k-1)} - \mu^{(k)} I &= Q^{(k)} R^{(k)} \\ A^{(k)} &= R^{(k)} Q^{(k)} + \mu^{(k)} I \end{aligned}$$

## Connection with shifted inverse iteration (cont'd)

- This implies

$$A^{(k)} = (Q^{(k)})^\top A^{(k-1)} Q^{(k)}$$

and by induction

$$A^{(k)} = (\underline{Q}^{(k)})^\top A \underline{Q}^{(k)}$$

which is unchanged from that in the QR algorithm without shifts

- However, the equation,  $A^k = \underline{Q}^{(k)} \underline{R}^{(k)}$ , in QR algorithm without shifts, is no longer true. Instead, we have the factorization

$$(A - \mu^{(k)} I)(A - \mu^{(k-1)} I) \cdots (A - \mu^{(1)} I) = \underline{Q}^{(k)} \underline{R}^{(k)}$$

a shifted variation on simultaneous iteration

- In other words,  $\underline{Q}^{(k)} = \prod_{j=1}^k Q^{(j)}$  is an orthogonalization of  $\prod_{j=1}^k (A - \mu^{(j)} I)$
- The first column of  $\underline{Q}^{(k)}$  is the result of applying shifted power iteration to  $\mathbf{e}_1$  using the shifts  $\mu^{(j)}$  and the last column is the result of applying  $k$  steps of shifted inverse iteration to  $\mathbf{e}_m$  with the same shifts
- If the shifts are good eigenvalue estimates, this last column of  $\underline{Q}^{(k)}$  converges quickly to an eigenvector

## Connection with Rayleigh quotient iteration

- To estimate the eigenvalue corresponding to the eigenvector approximated by the last column of  $\underline{Q}^{(k)}$ , it is natural to apply the Rayleigh quotient to this last column

$$\mu^{(k)} = \frac{(\mathbf{q}_m^{(k)})^\top A \mathbf{q}_m^{(k)}}{(\mathbf{q}_m^{(k)})^\top \mathbf{q}_m^{(k)}} = (\mathbf{q}_m^{(k)})^\top A \mathbf{q}_m^{(k)}$$

- If this number is chosen as the shift at every step, the eigenvalue and eigenvector estimates  $\mu^{(k)}$  and  $\mathbf{q}_m^{(k)}$  are identical to those that are computed by the Rayleigh quotient iteration with  $\mathbf{e}_m$
- Thus, the QR algorithm has cubic convergence in the sense that  $\mathbf{q}_m^{(k)}$  converges cubically to an eigenvector
- Notice that the Rayleigh quotient  $r(\mathbf{q}_m^{(k)})$  appears as the  $m, m$  entry of  $A^{(k)}$ , so it comes for free!

$$A_{mm}^{(k)} = \mathbf{e}_m^\top A^{(k)} \mathbf{e}_m = \mathbf{e}_m^\top \underline{Q}^{(k)\top} A \underline{Q}^{(k)} \mathbf{e}_m = \mathbf{q}_m^{(k)\top} A \mathbf{q}_m^{(k)}$$

- Thus the above equation of  $\mu^{(k)}$  is simply setting  $\mu^{(k)} = A_{mm}^{(k)}$ , which is known as the **Rayleigh quotient shift**

## Wilkinson shift

- Although the Rayleigh quotient shift gives cubic convergence, convergence is not guaranteed for all initial condition
- Consider

$$A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

The unshifted QR algorithm does not converge

$$\begin{aligned} A &= Q^{(1)}R^{(1)} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \\ A^{(1)} &= R^{(1)}Q^{(1)} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = A \end{aligned}$$

- The Rayleigh quotient shift  $\mu = A_{mm}$ , however, has no effect either, since  $A_{mm} = 0$
- The problem arises because of the symmetry of the eigenvalues, one is +1 and the other is -1
- Need an eigenvalue estimate that can break the symmetry

## Wilkinson shift (cont'd)

- Let  $B$  denote the lower rightmost  $2 \times 2$  submatrix  $A^{(k)}$

$$B = \begin{bmatrix} a_{m-1} & b_{m-1} \\ b_{m-1} & a_m \end{bmatrix}$$

- The **Wilkinson shift** is defined as that eigenvalue of  $B$  that is closer to  $a_m$  where in the case of a tie, one of the two eigenvalues of  $B$  is chosen arbitrarily
- A numerically stable formula for the Wilkinson shift is

$$\mu = a_m - \text{sign}(\delta) b_{m-1}^2 / (|\delta| + \sqrt{\delta^2 + b_{m-1}^2})$$

where  $\delta = (a_{m-1} - a_m)/2$  and if  $\delta = 0$ ,  $\text{sign}(\delta)$  can be arbitrarily set to 1 or -1



## Wilkinson shift (cont'd)

- Like Rayleigh quotient shift, the Wilkinson shift achieves cubic convergence in the generic case
- It can be shown that it achieves at least quadratic convergence in the worst case
- The QR algorithm with Wilkinson shift always converges

## Other eigenvalue algorithms

- Jacobi algorithm: one of the oldest ideas for computing eigenvalues
- Bisection method: when one does not need all the eigenvalues (e.g., largest 10%)
- Divide-and-conquer algorithm