

# EECS 275 Matrix Computation

Ming-Hsuan Yang

Electrical Engineering and Computer Science  
University of California at Merced  
Merced, CA 95344  
<http://faculty.ucmerced.edu/mhyang>



Lecture 11

# Overview

- Gram-Schmidt process
- QR decomposition
- Gram-Schmidt triangular orthogonalization

# Reading

- Chapter 7 and Chapter 8 of *Numerical Linear Algebra* by Lloyd Trefethen and David Bau
- Chapter 5 of *Matrix Computations* by Gene Golub and Charles Van Loan
- Chapter 5 of *Matrix Analysis and Applied Linear Algebra* by Carl Meyer

## Geometric properties of orthonormal basis

- Let the columns of  $U = [\mathbf{u}_1 \dots \mathbf{u}_n]$  are orthonormal,  $U^T U = I$
- If  $\mathbf{w} = U\mathbf{x}$ , then
  - ▶ mapping  $\mathbf{w} = U\mathbf{x}$  is isometric: it preserves distance (as  $\|\mathbf{w}\|^2 = \|\mathbf{x}\|^2$ )
  - ▶ inner products are preserved: if  $\mathbf{w}_1 = U\mathbf{x}_1$  and  $\mathbf{w}_2 = U\mathbf{x}_2$ , then  $\langle \mathbf{w}_1, \mathbf{w}_2 \rangle = \langle \mathbf{x}_1, \mathbf{x}_2 \rangle$
  - ▶ angles are preserved:  $\angle(\mathbf{w}_1, \mathbf{w}_2) = \angle(\mathbf{x}_1, \mathbf{x}_2)$
- Multiplication by  $U$  preserves inner products, angles, and distances
- It follows that  $U^{-1} = U^T$  and hence also  $UU^T = I$
- For any  $\mathbf{x}$ ,  $\mathbf{x} = UU^T\mathbf{x}$ , i.e.,

$$\mathbf{x} = \sum_{i=1}^n (\mathbf{u}_i^T \mathbf{x}) \mathbf{u}_i$$

- ▶  $\mathbf{u}_i^T \mathbf{x}$  is called the component of  $\mathbf{x}$  in the direction of  $\mathbf{u}_i$
- ▶  $\mathbf{a} = U^T \mathbf{x}$  resolves  $\mathbf{x}$  into the vector of its  $\mathbf{u}_i$  components
- ▶  $\mathbf{x} = U\mathbf{a}$  reconstructs  $\mathbf{x}$  from its  $\mathbf{u}_i$  components
- ▶  $\mathbf{x} = U\mathbf{a} = \sum_{i=1}^n a_i \mathbf{u}_i$  is called the expansion of  $\mathbf{x}$

# Examples

- Rotation by  $\theta$  in  $\mathbb{R}^2$  is given by

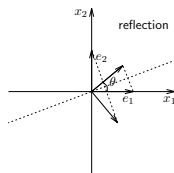
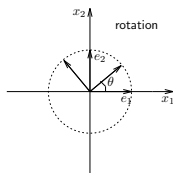
$$\mathbf{y} = U_\theta \mathbf{x}, U_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

since  $\mathbf{e}_1 = [\cos \theta, \sin \theta]^\top$ ,  $\mathbf{e}_2 = [-\sin \theta, \cos \theta]^\top$

- Reflection across line  $\mathbf{x}_2 = x_1 \tan(\theta/2)$  is given by

$$\mathbf{y} = U_\theta \mathbf{x}, U_\theta = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}$$

since  $\mathbf{e}_1 = [\cos \theta, \sin \theta]^\top$ ,  $\mathbf{e}_2 = [\sin \theta, -\cos \theta]^\top$



## Gram-Schmidt process

- Given independent vectors  $\mathbf{x}_1, \dots, \mathbf{x}_n \in \mathbb{R}^m$ , Gram-Schmidt process finds orthonormal vectors,  $\mathbf{q}_1, \dots, \mathbf{q}_n$  such that

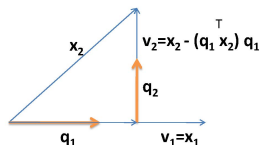
$$\text{span}(\mathbf{x}_1, \dots, \mathbf{x}_r) = \text{span}(\mathbf{q}_1, \dots, \mathbf{q}_r)$$

- Thus,  $\mathbf{q}_1, \dots, \mathbf{q}_r$  are orthonormal basis for  $\text{span}(\mathbf{x}_1, \dots, \mathbf{x}_r)$
- Idea: first orthogonalized each vector w.r.t. previous ones and then normalize result to have unit norm

- ▶  $\mathbf{v}_1 = \mathbf{x}_1$
- ▶  $\mathbf{q}_1 = \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|}$  (normalize)
- ▶  $\mathbf{v}_2 = \mathbf{x}_2 - (\mathbf{q}_1^\top \mathbf{x}_2)\mathbf{q}_1$  (remove  $\mathbf{q}_1$  component from  $\mathbf{x}_2$ )
- ▶  $\mathbf{q}_2 = \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|}$  (normalize)
- ▶  $\mathbf{v}_3 = \mathbf{x}_3 - (\mathbf{q}_1^\top \mathbf{x}_3)\mathbf{q}_1 - (\mathbf{q}_2^\top \mathbf{x}_3)\mathbf{q}_2$  (remove,  $\mathbf{q}_1, \mathbf{q}_2$  components)
- ▶  $\mathbf{q}_3 = \frac{\mathbf{v}_3}{\|\mathbf{v}_3\|}$
- ▶ etc.

- Find orthonormal basis incrementally

# Geometric interpretation of Gram-Schmidt process



- Gram-Schmidt process:

- ▶  $v_1 = x_1$
- ▶  $q_1 = \frac{v_1}{\|v_1\|}$  (normalize)
- ▶  $v_2 = x_2 - (q_1^T x_2)q_1$  (remove  $q_1$  component from  $x_2$ )
- ▶  $q_2 = \frac{v_2}{\|v_2\|}$  (normalize)
- ▶  $v_3 = x_3 - (q_1^T x_3)q_1 - (q_2^T x_3)q_2$  (remove,  $q_1, q_2$  components)
- ▶  $q_3 = \frac{v_3}{\|v_3\|}$
- ▶ etc.

- $\forall i$ , we have

$$\begin{aligned}x_i &= (q_1^T x_i)q_1 + (q_2^T x_i)q_2 + \cdots + (q_{i-1}^T x_i)q_{i-1} + \|v_i\|q_i \\ &= r_{1i}q_1 + r_{2i}q_2 + \cdots + r_{ii}q_i\end{aligned}$$

## QR decomposition

- In matrix form,  $A = QR$  where  $A \in \mathbb{R}^{m \times n}$ ,  $Q \in \mathbb{R}^{m \times n}$ ,  $R \in \mathbb{R}^{n \times n}$ :

$$\underbrace{\begin{bmatrix} \mathbf{x}_1 & \mathbf{x}_2 & \cdots & \mathbf{x}_n \end{bmatrix}}_A = \underbrace{\begin{bmatrix} \mathbf{q}_1 & \mathbf{q}_2 & \cdots & \mathbf{q}_n \end{bmatrix}}_Q \underbrace{\begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ 0 & r_{22} & \cdots & r_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & r_{nn} \end{bmatrix}}_R$$

- $Q^T Q = I$ , and  $R$  is upper triangular and invertible
- Usually computed using a variation of Gram-Schmidt process which is less sensitive to numerical errors
- Can also be computed by Householder transformation or Givens rotations
- Columns of  $Q$  are orthonormal basis in  $\text{ran}(A)$

$$Q^T A = R$$



## General Gram-Schmidt process

- If  $\mathbf{x}_1, \dots, \mathbf{x}_n$  are dependent, we find  $\mathbf{v}_j = 0$  for some  $j$ , which means  $\mathbf{x}_j$  is linearly dependent on  $\mathbf{x}_1, \dots, \mathbf{x}_{j-1}$
- Modified algorithm: when we have  $\mathbf{v}_j = 0$ , skip to the next vector  $\mathbf{x}_{j+1}$  and continue

```
k = 0
for i = 1, ..., n
{
  v = x_i - \sum_{j=1}^k q_j q_j^T x_i;
  if v \neq 0 {k = k + 1; q_k = \frac{v}{\|v\|}};
}
```

## Example

- Consider the matrix

$$A = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \\ -1 & -1 & -1 \end{bmatrix}$$

$$\mathbf{v}_1 = \mathbf{x}_1, \quad \mathbf{q}_1 = \frac{\mathbf{x}_1}{\|\mathbf{x}_1\|} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \end{bmatrix}$$

$$\mathbf{v}_2 = \mathbf{x}_2 - (\mathbf{q}_1^\top \mathbf{x}_2)\mathbf{q}_1 = \begin{bmatrix} 0 \\ 2 \\ 0 \\ 0 \end{bmatrix}, \quad \mathbf{q}_2 = \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

$$\mathbf{v}_3 = \mathbf{x}_3 - (\mathbf{q}_1^\top \mathbf{x}_3)\mathbf{q}_1 - (\mathbf{q}_2^\top \mathbf{x}_3)\mathbf{q}_2 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{q}_3 = \frac{\mathbf{v}_3}{\|\mathbf{v}_3\|} = \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

## Example (cont'd)

- Then we have

$$R = Q^T A = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{3}} \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{3}} \end{bmatrix}^T \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \\ -1 & -1 & -1 \end{bmatrix} = \begin{bmatrix} \sqrt{2} & \sqrt{2} & 2\sqrt{2} \\ 0 & -2 & -1 \\ 0 & 0 & \sqrt{3} \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 2 & 1 \\ 0 & 0 & 1 \\ -1 & -1 & -1 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{3}} \\ 0 & -1 & 0 \\ 0 & 0 & \frac{1}{\sqrt{3}} \\ -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{3}} \end{bmatrix} \begin{bmatrix} \sqrt{2} & \sqrt{2} & 2\sqrt{2} \\ 0 & -2 & -1 \\ 0 & 0 & \sqrt{3} \end{bmatrix}$$

## Properties of QR decomposition

- Find orthonormal basis for  $\text{ran}(A)$  directly
- Let  $A = BC$  with  $B \in \mathbb{R}^{m \times p}$ ,  $C \in \mathbb{R}^{p \times n}$ ,  $p = \text{rank}(A)$
- To check whether  $\mathbf{y} \in \text{span}(\mathbf{x}_1, \dots, \mathbf{x}_n)$ : apply Gram-Schmidt procedure to  $[\mathbf{x}_1, \dots, \mathbf{x}_n, \mathbf{y}]$
- If  $A = Q_1 R_1$  with  $\text{rank}(A) = p$ , the **full QR factorization** is

$$A = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix} \begin{bmatrix} R_1 \\ 0 \end{bmatrix}$$

where  $\begin{bmatrix} Q_1 & Q_2 \end{bmatrix}$  is orthogonal, i.e., columns of  $Q_2 \in \mathbb{R}^{m \times (m-p)}$  are orthonormal, orthogonal to  $Q_1$

- To find  $Q_2$ , one can use any matrix  $\tilde{A}$  s.t.  $[A \ \tilde{A}]$  is full rank (e.g.,  $\tilde{A} = I$ ), and then apply general Gram-Schmidt process
- $Q_1$  are orthonormal vectors obtained from columns of  $A$
- $Q_2$  are orthonormal vectors obtained from extra columns  $\tilde{A}$

# Complementary subspaces

- $\text{ran}(Q_1)$  and  $\text{ran}(Q_2)$  are **complementary subspaces** since
  - ▶ they are orthogonal (i.e., every vector in the first subspace is orthogonal to every vector in the second subspace)
  - ▶ the sum is  $\mathbb{R}^m$  (i.e., every vector in  $\mathbb{R}^m$  can be expressed as a sum of two vectors, one from each subspace)

$$\text{ran}(Q_1)^\perp + \text{ran}(Q_2) = \mathbb{R}^m \quad \text{ran}(Q_2) = \text{ran}(Q_1)^\perp \quad (\text{ran}(Q_1) = \text{ran}(Q_2)^\perp)$$

- We know  $\text{ran}(Q_1) = \text{ran}(A)$ ; what is its orthogonal complement  $\text{ran}(Q_2)$ ?

## Complementary subspaces

- From  $A^T = [ R_1^T \quad 0 ] \begin{bmatrix} Q_1^T \\ Q_2^T \end{bmatrix}$ , we have

$$A^T \mathbf{z} = 0 \iff Q_1^T \mathbf{z} = 0 \iff \mathbf{z} \in \text{ran}(Q_2)$$

so  $\text{ran}(Q_2) = \text{ran}(A^T)$  (i.e., columns of  $Q_2$  are an orthonormal basis for  $\text{ran}(A^T)$ )

- We conclude:  $\text{ran}(A)$  and  $\text{null}(A^T)$  are complementary subspaces
  - ▶  $\text{ran}(A) \overset{\perp}{+} \text{null}(A^T) = \mathbb{R}^m$  (recall  $A \in \mathbb{R}^{m \times p}$ )
  - ▶  $\text{ran}(A)^\perp = \text{null}(A^T)$  (and  $\text{null}(A^T)^\perp = \text{ran}(A)$ )
  - ▶ called **orthogonal decomposition** induced by  $A \in \mathbb{R}^{m \times p}$

## Least squares via QR decomposition

- $A \in \mathbb{R}^{m \times n}$ ,  $A = QR$  with  $Q^T Q = I$ ,  $R \in \mathbb{R}^{n \times n}$
- The pseudo inverse is

$$(A^T A)^{-1} A^T = (R^T Q^T Q R)^{-1} R^T Q^T = R^{-1} Q^T$$

- The projected point,  $\mathbf{x}_{ls} = R^{-1} Q^T \mathbf{y}$
- The projection matrix

$$A(A^T A)^{-1} A^T = A R^{-1} Q^T = Q Q^T$$

## Least squares via full QR factorization

- Full QR factorization

$$A = [ Q_1 \quad Q_2 ] \begin{bmatrix} R_1 \\ 0 \end{bmatrix}$$

where  $[ Q_1 \quad Q_2 ] \in \mathbb{R}^{m \times m}$  is orthogonal,  $R_1 \in \mathbb{R}^{n \times n}$  is upper triangular and invertible

- Multiplication by orthogonal matrix

$$\begin{aligned} \|Ax - \mathbf{y}\|^2 &= \left\| [ Q_1 \quad Q_2 ] \begin{bmatrix} R_1 \\ 0 \end{bmatrix} \mathbf{x} - \mathbf{y} \right\|^2 \\ &= \left\| [ Q_1 \quad Q_2 ]^T [ Q_1 \quad Q_2 ] \begin{bmatrix} R_1 \\ 0 \end{bmatrix} \mathbf{x} - [ Q_1 \quad Q_2 ]^T \mathbf{y} \right\|^2 \\ &= \left\| \begin{bmatrix} R_1 \mathbf{x} - Q_1^T \mathbf{y} \\ -Q_2^T \mathbf{y} \end{bmatrix} \right\|^2 \\ &= \left\| R_1 \mathbf{x} - Q_1^T \mathbf{y} \right\|^2 + \left\| Q_2^T \mathbf{y} \right\|^2 \end{aligned}$$

- Can be minimized by choosing  $\mathbf{x}_{ls} = R_1^{-1} Q_1^T \mathbf{y}$



## Least squares via full QR factorization (cont'd)

- Least squares minimization

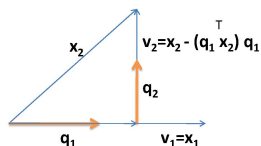
$$\|A\mathbf{x} - \mathbf{y}\|^2 = \|R_1\mathbf{x} - Q_1^T\mathbf{y}\|^2 + \|Q_2^T\mathbf{y}\|^2$$

- Optimal solution  $\mathbf{x}_{ls} = R_1^{-1}Q_1^T\mathbf{y}$
- Residual of the optimal  $\mathbf{x}$  is

$$A\mathbf{x}_{ls} - \mathbf{y} = -Q_2Q_2^T\mathbf{y}$$

- $Q_1Q_1^T$  gives projection onto  $\text{ran}(A)$
- $Q_2Q_2^T$  gives projection onto  $\text{ran}(A)^\perp$

# Gram-Schmidt as triangular orthogonalization



## Steps:

- ▶  $v_1 = x_1$
- ▶  $q_1 = \frac{v_1}{\|v_1\|}$  (normalize)
- ▶  $v_2 = x_2 - (q_1^T x_2)q_1 = (I - q_1 q_1^T)x_2$  (remove  $q_1$  component from  $x_2$ )
- ▶  $q_2 = \frac{v_2}{\|v_2\|}$  (normalize)
- ▶  $v_3 = x_3 - (q_1^T x_3)q_1 - (q_2^T x_3)q_2 = (I - q_1 q_1^T - q_2 q_2^T)x_3 = (I - q_1 q_1^T)(I - q_2 q_2^T)x_3$  (remove,  $q_1, q_2$  components)
- ▶  $q_3 = \frac{v_3}{\|v_3\|}$
- ▶ etc.

$$\begin{bmatrix} x_1 & x_2 & \cdots & x_n \end{bmatrix} = \begin{bmatrix} q_1 & q_2 & \cdots & q_n \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ & r_{22} & \cdots & \\ & & \ddots & \\ & & & r_{nn} \end{bmatrix}$$

## Gram-Schmidt as triangular orthogonalization (cont'd)

$$[\mathbf{x}_1 \quad \mathbf{x}_2 \quad \cdots \quad \mathbf{x}_n] = [\mathbf{q}_1 \quad \mathbf{q}_2 \quad \cdots \quad \mathbf{q}_n] \begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ & r_{22} & \cdots & \\ & & \ddots & \vdots \\ & & & r_{nn} \end{bmatrix}$$

$$\mathbf{x}_1 = r_{11}\mathbf{q}_1$$

$$\mathbf{x}_2 = r_{12}\mathbf{q}_1 + r_{22}\mathbf{q}_2 = \frac{r_{12}}{r_{11}}\mathbf{x}_1 + r_{22}\mathbf{q}_2 = (\mathbf{q}_1^\top \mathbf{x}_2)\mathbf{q}_1 + r_{22}\mathbf{q}_2$$

$$\mathbf{x}_3 = r_{13}\mathbf{q}_1 + r_{23}\mathbf{q}_2 + r_{33}\mathbf{q}_3 = (\mathbf{q}_1^\top \mathbf{x}_3)\mathbf{q}_1 + (\mathbf{q}_2^\top \mathbf{x}_3)\mathbf{q}_2 + r_{33}\mathbf{q}_3$$

$\vdots$

$$\mathbf{x}_n = r_{1n}\mathbf{q}_1 + r_{2n}\mathbf{q}_2 + \cdots + r_{nn}\mathbf{q}_n$$

$$\mathbf{x}_i = (\mathbf{q}_1^\top \mathbf{x}_i)\mathbf{q}_1 + (\mathbf{q}_2^\top \mathbf{x}_i)\mathbf{q}_2 + \cdots + (\mathbf{q}_{i-1}^\top \mathbf{x}_i)\mathbf{q}_{i-1} + \|\tilde{\mathbf{q}}_i\|\mathbf{q}_i$$

$$= r_{1i}\mathbf{q}_1 + r_{2i}\mathbf{q}_2 + \cdots + r_{ii}\mathbf{q}_i$$

$$r_{ij} = \mathbf{q}_i^\top \mathbf{x}_j \quad (i \neq j)$$

## Gram-Schmidt as triangular orthogonalization (cont'd)

- Gram-Schmidt process

$$[\mathbf{x}_1 \quad \mathbf{x}_2 \quad \cdots \quad \mathbf{x}_n] = [\mathbf{q}_1 \quad \mathbf{q}_2 \quad \cdots \quad \mathbf{q}_n] \begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ & r_{22} & \cdots & \\ & & \ddots & \vdots \\ & & & r_{nn} \end{bmatrix}$$

- At the  $j$ -th step, want to find a unit vector  $\mathbf{q}_j \in \{\mathbf{x}_1, \dots, \mathbf{x}_j\}$  that is orthogonal to  $\mathbf{q}_1, \dots, \mathbf{q}_{j-1}$

$$\mathbf{v}_j = \mathbf{x}_j - (\mathbf{q}_1^\top \mathbf{x}_j)\mathbf{q}_1 - (\mathbf{q}_2^\top \mathbf{x}_j)\mathbf{q}_2 - \cdots - (\mathbf{q}_{j-1}^\top \mathbf{x}_j)\mathbf{q}_{j-1}$$

$$\mathbf{q}_1 = \frac{\mathbf{x}_1}{r_{11}}$$

$$\mathbf{q}_2 = \frac{\mathbf{x}_2 - r_{12}\mathbf{q}_1}{r_{22}} = \frac{(I - \mathbf{q}_1\mathbf{q}_1^\top)\mathbf{x}_2}{\|(I - \mathbf{q}_1\mathbf{q}_1^\top)\mathbf{x}_2\|} = \frac{P_2\mathbf{x}_2}{\|P_2\mathbf{x}_2\|}$$

$\vdots$

$$\mathbf{q}_n = \frac{\mathbf{x}_n - \sum_{i=1}^{n-1} r_{in}\mathbf{q}_i}{r_{nn}} = \frac{(I - Q_{n-1}Q_{n-1}^\top)\mathbf{x}_n}{\|(I - Q_{n-1}Q_{n-1}^\top)\mathbf{x}_n\|} = \frac{P_n\mathbf{x}_n}{\|P_n\mathbf{x}_n\|}$$

$$r_{ij} = \mathbf{q}_i^\top \mathbf{x}_j \quad (i \neq j)$$

$$|r_{jj}| = \|\mathbf{x}_j - \sum_{i=1}^j r_{ij}\mathbf{q}_i\|_2 \quad (\text{often choose } r_{jj} > 0)$$

## Gram-Schmidt as triangular orthogonalization (cont'd)

- Let  $A \in \mathbb{R}^{m \times n}$ ,  $m \geq n$  be a matrix of full rank with columns  $\mathbf{x}_i$ , consider the sequence of formulas

$$\mathbf{q}_1 = \frac{P_1 \mathbf{x}_1}{\|P_1 \mathbf{x}_1\|}, \quad \mathbf{q}_2 = \frac{P_2 \mathbf{x}_2}{\|P_2 \mathbf{x}_2\|}, \quad \dots, \quad \mathbf{q}_n = \frac{P_n \mathbf{x}_n}{\|P_n \mathbf{x}_n\|}$$

where  $P_j \in \mathbb{R}^{m \times m}$  of rank  $m - (j - 1)$  projects  $\mathbf{x}$  onto the space orthogonal to  $\mathbf{q}_1, \dots, \mathbf{q}_{j-1}$  ( $P_1 = I$  when  $j = 1$ )

- Projection  $P_j$  can be represented explicitly
- Let  $Q_{j-1}$  denote the  $m \times (j - 1)$  matrix containing the first  $j - 1$  columns of  $Q$

$$Q_{j-1} = [\mathbf{q}_1 \quad \mathbf{q}_2 \quad \dots \quad \mathbf{q}_{j-1}]$$

then

$$P_j = I - Q_{j-1} Q_{j-1}^T$$

## Modified Gram-Schmidt process

- Recall for rank-one orthogonal projection with  $\mathbf{q} \in \mathbb{R}^m$

$$P_{\mathbf{q}} = \frac{\mathbf{q}\mathbf{q}^{\top}}{\mathbf{q}^{\top}\mathbf{q}}$$

- The complements are rank  $m - 1$  orthogonal projections

$$P_{\perp\mathbf{q}} = I - \frac{\mathbf{q}\mathbf{q}^{\top}}{\mathbf{q}^{\top}\mathbf{q}}$$

- By definition of  $P_j$

$$P_j = P_{\perp\mathbf{q}_{j-1}} \cdots P_{\perp\mathbf{q}_2} P_{\perp\mathbf{q}_1}$$

where  $P_1 = I$ , and thus

$$\mathbf{v}_j = P_{\perp\mathbf{q}_{j-1}} \cdots P_{\perp\mathbf{q}_2} P_{\perp\mathbf{q}_1} \mathbf{x}_j$$

## Modified Gram-Schmidt process (cont'd)

- For numerical stability, evaluating the following formulas in order (for now consider an algorithm is considered as stable if it is not too sensitive to the effects of rounding errors)

$$\begin{aligned} \mathbf{v}_j^{(1)} &= \mathbf{x}_j, \\ \mathbf{v}_j^{(2)} &= P_{\perp \mathbf{q}_1} \mathbf{v}_j^{(1)} = \mathbf{v}_j^{(1)} - \mathbf{q}_1 \mathbf{q}_1^\top \mathbf{v}_j^{(1)}, \\ \mathbf{v}_j^{(3)} &= P_{\perp \mathbf{q}_2} \mathbf{v}_j^{(2)} = \mathbf{v}_j^{(2)} - \mathbf{q}_2 \mathbf{q}_2^\top \mathbf{v}_j^{(2)}, \\ &\vdots \\ \mathbf{v}_j &= \mathbf{v}_j^{(j)} = P_{\perp \mathbf{q}_{j-1}} \mathbf{v}_j^{(j-1)} = \mathbf{v}_j^{(j-1)} - \mathbf{q}_{j-1} \mathbf{q}_{j-1}^\top \mathbf{v}_j^{(j-1)} \end{aligned}$$

- Projection matrix  $P_{\perp \mathbf{q}_i}$  can be applied to  $\mathbf{v}_j^{(i)}$  for each  $j > i$  immediately after  $\mathbf{q}_i$  is known
- $\mathbf{v}_1 = \mathbf{v}_1^{(1)} = \mathbf{x}_1$ ,  $\mathbf{q}_1 = \frac{1}{r_{11}} \mathbf{v}_1^{(1)}$
- $\mathbf{v}_2 = \mathbf{v}_2^{(2)} = \mathbf{v}_2^{(1)} - \mathbf{q}_1 \mathbf{q}_1^\top \mathbf{v}_2^{(1)} = \mathbf{v}_2^{(1)} - \left(\frac{1}{r_{11}} \mathbf{v}_1^{(1)}\right) r_{12}$
- $\mathbf{v}_3 = \mathbf{v}_3^{(3)} = \mathbf{v}_3^{(2)} - \mathbf{q}_2 \mathbf{q}_2^\top \mathbf{v}_3^{(2)}$ ,  
 $\mathbf{v}_3^{(2)} = \mathbf{v}_3^{(1)} - \mathbf{q}_1 \mathbf{q}_1^\top \mathbf{v}_3^{(1)} = \mathbf{v}_3^{(1)} - \left(\frac{1}{r_{11}} \mathbf{v}_1^{(1)}\right) r_{13}$

# Modified Gram-Schmidt algorithm

- Steps

$$\begin{aligned} \mathbf{v}_j^{(1)} &= \mathbf{x}_j, \\ &\vdots \\ \mathbf{v}_j &= \mathbf{v}_j^{(j)} = P_{\perp \mathbf{q}_{j-1}} \mathbf{v}_j^{(j-1)} = \mathbf{v}_j^{(j-1)} - \mathbf{q}_{j-1} \mathbf{q}_{j-1}^\top \mathbf{v}_j^{(j-1)} \end{aligned}$$

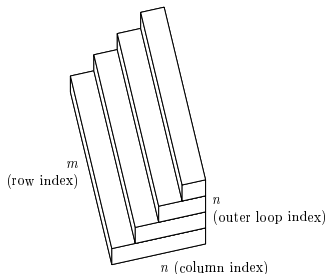
- Algorithm:

```
for  $i = 1$  to  $n$  do  
   $\mathbf{v}_i = \mathbf{x}_i$   
end for  
for  $i = 1$  to  $n$  do  
   $r_{ii} = \|\mathbf{v}_i\|$   
   $\mathbf{q}_i = \frac{\mathbf{v}_i}{r_{ii}}$   
  for  $j = i + 1$  to  $n$  do  
     $r_{ij} = \mathbf{q}_i^\top \mathbf{v}_j$   
     $\mathbf{v}_j = \mathbf{v}_j - r_{ij} \mathbf{q}_i$   
  end for  
end for
```



# Complexity of Gram-Schmidt process

- Algorithmically, complexity of general or modified Gram-Schmidt process requires  $\sim 2mn^2$  flops for an  $m \times n$  matrix
- Geometrically, it can be easily seen that the complexity is  $\sim 2mn^2$  flops



- As  $m, n \rightarrow \infty$ , the figure converges to a right triangular prism, with volume  $mn^2/2$ , multiply four flops per unit volume gives  $2mn^2$  flops

## Gram-Schmidt as triangular orthogonalization

- The projection matrix  $P_j = I - Q_{j-1}Q_{j-1}^T$  can be represented explicitly

$$\mathbf{x}_1 = r_{11}\mathbf{q}_1 \quad (\mathbf{q}_1 = \frac{1}{r_{11}}\mathbf{x}_1)$$

$$\mathbf{x}_2 = r_{12}\mathbf{q}_1 + r_{22}\mathbf{q}_2 = \frac{r_{12}}{r_{11}}\mathbf{x}_1 + r_{22}\mathbf{q}_2 \quad (\mathbf{q}_2 = \frac{1}{r_{22}}(\mathbf{x}_2 - \frac{r_{12}}{r_{11}}\mathbf{x}_1))$$

$$\mathbf{x}_3 = r_{13}\mathbf{q}_1 + r_{23}\mathbf{q}_2 + r_{33}\mathbf{q}_3 = \frac{r_{13}}{r_{11}}\mathbf{x}_1 + r_{23}\mathbf{q}_2 + r_{33}\mathbf{q}_3$$

$\vdots$

$$\mathbf{x}_i = r_{1i}\mathbf{q}_1 + r_{2i}\mathbf{q}_2 + \cdots + r_{ii}\mathbf{q}_i$$

- The first iteration multiply the first column  $\mathbf{x}_1$  by  $1/r_{11}$  and then subtract  $r_{1j}$  times the result from each of the remaining columns  $\mathbf{x}_j$
- Equivalent to right-multiplication by a matrix  $R_1$

$$[\mathbf{v}_1 \quad \mathbf{v}_2 \quad \cdots \quad \mathbf{v}_n] \begin{bmatrix} \frac{1}{r_{11}} & \frac{-r_{12}}{r_{11}} & \frac{-r_{13}}{r_{11}} & \cdots \\ & 1 & & \\ & & 1 & \\ & & & \ddots \end{bmatrix} = [\mathbf{q}_1 \quad \mathbf{v}_2^{(2)} \quad \cdots \quad \mathbf{v}_n^{(2)}]$$

## Gram-Schmidt triangular orthogonalization (cont'd)

- At step  $i$  the modified Gram-Schmidt algorithm subtracts  $r_{ij}/r_{ii}$  times column  $i$  of the current  $A$  from columns  $j > i$  and replaces column  $i$  by  $1/r_{ii}$  times itself
- This corresponds to multiplication by an upper triangular matrix  $R_i$

$$R_2 = \begin{bmatrix} 1 & & & & \\ & \frac{1}{r_{22}} & \frac{-r_{23}}{r_{22}} & \dots & \\ & & 1 & & \\ & & & \ddots & \\ & & & & \ddots \end{bmatrix}, \quad R_3 = \begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & \frac{1}{r_{33}} & \frac{-r_{34}}{r_{33}} & \dots \\ & & & \ddots & \\ & & & & \ddots \end{bmatrix}, \quad \dots$$

- At the end, we have

$$A \underbrace{R_1 R_2 \cdots R_n}_{R^{-1}} = Q$$

- This shows that the Gram-Schmidt algorithm is a method of triangular orthogonalization